

Mixing Time and Stationary Expected Social Welfare of Logit Dynamics

Francesco Pasquale

Dipartimento di Informatica “R. Capocelli”
Università di Salerno

joint work-in-progress with

Vincenzo Auletta, Diodato Ferraioli, and Giuseppe Persiano

Roma, June 17, 2010

Outline

Framework Description

Examples

Research Directions

Game Theory

...in one slide

$$\mathcal{G} = ([n], \mathcal{S}, \mathcal{U})$$

- ▶ $[n] = \{1, \dots, n\}$ players;
- ▶ $\mathcal{S} = \{S_1, \dots, S_n\}; \quad S_i = \{ \text{actions for player } i \};$
- ▶ $\mathcal{U} = \{u_1, \dots, u_n\}; \quad u_i : S_1 \times \dots \times S_n \rightarrow \mathbb{R}$ utility functions

Game Theory

...in one slide

$$\mathcal{G} = ([n], \mathcal{S}, \mathcal{U})$$

- ▶ $[n] = \{1, \dots, n\}$ players;
- ▶ $\mathcal{S} = \{S_1, \dots, S_n\}$; $S_i = \{ \text{actions for player } i \}$;
- ▶ $\mathcal{U} = \{u_1, \dots, u_n\}$; $u_i : S_1 \times \dots \times S_n \rightarrow \mathbb{R}$ utility functions

$\mathbf{x} = (x_1, \dots, x_n) \in S_1 \times \dots \times S_n$ **pure Nash** equilibrium if for every $i \in [n]$ and for every $y \in S_i$

$$u_i(\mathbf{x}_{-i}, y) \leq u_i(\mathbf{x})$$

Game Theory

...in one slide

$$\mathcal{G} = ([n], \mathcal{S}, \mathcal{U})$$

- ▶ $[n] = \{1, \dots, n\}$ players;
- ▶ $\mathcal{S} = \{S_1, \dots, S_n\}$; $S_i = \{ \text{actions for player } i \}$;
- ▶ $\mathcal{U} = \{u_1, \dots, u_n\}$; $u_i : S_1 \times \dots \times S_n \rightarrow \mathbb{R}$ utility functions

$\mathbf{x} = (x_1, \dots, x_n) \in S_1 \times \dots \times S_n$ **pure Nash** equilibrium if for every $i \in [n]$ and for every $y \in S_i$

$$u_i(\mathbf{x}_{-i}, y) \leq u_i(\mathbf{x})$$

$\boldsymbol{\mu} = (\mu_1, \dots, \mu_n) \in \Delta(S_1) \times \dots \times \Delta(S_n)$ **mixed Nash** equilibrium if for every $i \in [n]$ and for every $\sigma \in \Delta(S_i)$

$$\mathbf{E}_{(\boldsymbol{\mu}_{-i}, \sigma)} [u_i] \leq \mathbf{E}_{\boldsymbol{\mu}} [u_i]$$

Dynamics

Reaching equilibria

Dynamics: Choose a player, update her strategy, repeat.

Dynamics

Reaching equilibria

Dynamics: Choose a player, update her strategy, repeat.

Best response dynamics

At her turn, player i chooses the action $y \in S_i$ that maximizes her utility

$$u_i(\mathbf{x}_{-i}, y) \geq u_i(\mathbf{x}_{-i}, z) \text{ for every } z \in S_i$$

Dynamics

Reaching equilibria

Dynamics: Choose a player, update her strategy, repeat.

Best response dynamics

At her turn, player i chooses the action $y \in S_i$ that maximizes her utility

$$u_i(\mathbf{x}_{-i}, y) \geq u_i(\mathbf{x}_{-i}, z) \text{ for every } z \in S_i$$

Questions

► Convergence

Dynamics

Reaching equilibria

Dynamics: Choose a player, update her strategy, repeat.

Best response dynamics

At her turn, player i chooses the action $y \in S_i$ that maximizes her utility

$$u_i(\mathbf{x}_{-i}, y) \geq u_i(\mathbf{x}_{-i}, z) \text{ for every } z \in S_i$$

Questions

- ▶ Convergence
If yes then...
- ▶ **Speed of convergence.**

Randomized Best Response

Logit Dynamics

Randomized Best Response: Choose for the next round strategy y with probability proportional to the returned utility.

Randomized Best Response

Logit Dynamics

Randomized Best Response: Choose for the next round strategy y with probability proportional to the returned utility.

$$\mathbf{x} \in S_1 \times \cdots \times S_n, \quad i \in [n], \quad y \in S_i \quad \Rightarrow \quad \sigma_i(y \mid \mathbf{x}) \sim e^{\beta u_i(\mathbf{x}_{-i}, y)}$$

Randomized Best Response

Logit Dynamics

Randomized Best Response: Choose for the next round strategy y with probability proportional to the returned utility.

$$\mathbf{x} \in S_1 \times \cdots \times S_n, \quad i \in [n], \quad y \in S_i \quad \Rightarrow \quad \sigma_i(y \mid \mathbf{x}) \sim e^{\beta u_i(\mathbf{x}_{-i}, y)}$$

$$\sigma_i(y \mid \mathbf{x}) = \frac{e^{\beta u_i(\mathbf{x}_{-i}, y)}}{\sum_{z \in S_i} e^{\beta u_i(\mathbf{x}_{-i}, z)}}$$

β = “Inverse noise”

Observation

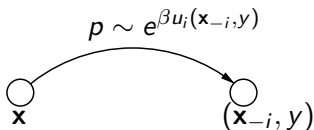
- ▶ $\beta = 0$ players play uniformly at random;
- ▶ $\beta \rightarrow \infty$ players play best response (u.a.r. over best responses if more than one)

Logit Dynamics

Description

Logit dynamics [Blume, GEB'93]

From any profile \mathbf{x} , choose a player $i \in [n]$ u.a.r and update her action with probability $\sigma_i(\cdot | \mathbf{x})$.



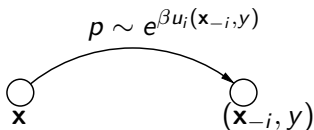
$$P(\mathbf{x}, (\mathbf{x}_{-i}, y)) = \frac{1}{n} \sigma_i(y | \mathbf{x})$$

Logit Dynamics

Description

Logit dynamics [Blume, GEB'93]

From any profile \mathbf{x} , choose a player $i \in [n]$ u.a.r and update her action with probability $\sigma_i(\cdot | \mathbf{x})$.



$$P(\mathbf{x}, (\mathbf{x}_{-i}, y)) = \frac{1}{n} \sigma_i(y | \mathbf{x})$$

This process defines an ergodic Markov chain

Markov chains

...in one slide

$$\{X_t : t \in \mathbb{N}\}, (\Omega, P).$$

Markov chains

...in one slide

$\{X_t : t \in \mathbb{N}\}, (\Omega, P).$

- **Irreducible:** for every $\mathbf{x}, \mathbf{y} \in \Omega$, $\exists t \in \mathbb{N} : P^t(\mathbf{x}, \mathbf{y}) > 0$;

Markov chains

...in one slide

$\{X_t : t \in \mathbb{N}\}, (\Omega, P).$

- ▶ Irreducible: for every $\mathbf{x}, \mathbf{y} \in \Omega$, $\exists t \in \mathbb{N} : P^t(\mathbf{x}, \mathbf{y}) > 0$;
- ▶ **Aperiodic**: for every \mathbf{x} , $\gcd \{t \geq 1 : P^t(\mathbf{x}, \mathbf{x}) > 0\} = 1$;

Markov chains

...in one slide

$\{X_t : t \in \mathbb{N}\}, (\Omega, P).$

- ▶ Irreducible: for every $\mathbf{x}, \mathbf{y} \in \Omega$, $\exists t \in \mathbb{N} : P^t(\mathbf{x}, \mathbf{y}) > 0$;
- ▶ Aperiodic: for every \mathbf{x} , $\gcd \{t \geq 1 : P^t(\mathbf{x}, \mathbf{x}) > 0\} = 1$;
- ▶ **Stationary distribution**: $\pi \in \Delta(\Omega)$, $\pi P = \pi$.

Markov chains

...in one slide

$\{X_t : t \in \mathbb{N}\}, (\Omega, P).$

- ▶ Irreducible: for every $\mathbf{x}, \mathbf{y} \in \Omega$, $\exists t \in \mathbb{N} : P^t(\mathbf{x}, \mathbf{y}) > 0$;
- ▶ Aperiodic: for every \mathbf{x} , $\gcd \{t \geq 1 : P^t(\mathbf{x}, \mathbf{x}) > 0\} = 1$;
- ▶ Stationary distribution: $\pi \in \Delta(\Omega)$, $\pi P = \pi$.

Irreducible + Aperiodic = Ergodic \implies

$\implies \pi$ is unique and $P^t(\mathbf{x}, \cdot) \rightarrow \pi$

Markov chains

...in one slide

$\{X_t : t \in \mathbb{N}\}, (\Omega, P).$

- ▶ Irreducible: for every $\mathbf{x}, \mathbf{y} \in \Omega$, $\exists t \in \mathbb{N} : P^t(\mathbf{x}, \mathbf{y}) > 0$;
- ▶ Aperiodic: for every \mathbf{x} , $\gcd \{t \geq 1 : P^t(\mathbf{x}, \mathbf{x}) > 0\} = 1$;
- ▶ Stationary distribution: $\pi \in \Delta(\Omega)$, $\pi P = \pi$.

Irreducible + Aperiodic = Ergodic \implies

$\implies \pi$ is unique and $P^t(\mathbf{x}, \cdot) \rightarrow \pi$

- ▶ **Total variation distance** $\mu, \nu \in \Delta(\Omega)$

$$\|\mu - \nu\| = \max_{A \subseteq \Omega} |\mu(A) - \nu(A)| = \frac{1}{2} \sum_{\mathbf{x} \in \Omega} |\mu(\mathbf{x}) - \nu(\mathbf{x})|$$

Markov chains

...in one slide

$\{X_t : t \in \mathbb{N}\}, (\Omega, P).$

- ▶ Irreducible: for every $\mathbf{x}, \mathbf{y} \in \Omega$, $\exists t \in \mathbb{N} : P^t(\mathbf{x}, \mathbf{y}) > 0$;
- ▶ Aperiodic: for every \mathbf{x} , $\gcd \{t \geq 1 : P^t(\mathbf{x}, \mathbf{x}) > 0\} = 1$;
- ▶ Stationary distribution: $\pi \in \Delta(\Omega)$, $\pi P = \pi$.

Irreducible + Aperiodic = Ergodic \implies

$\implies \pi$ is unique and $P^t(\mathbf{x}, \cdot) \rightarrow \pi$

- ▶ Total variation distance $\mu, \nu \in \Delta(\Omega)$

$$\|\mu - \nu\| = \max_{A \subseteq \Omega} |\mu(A) - \nu(A)| = \frac{1}{2} \sum_{\mathbf{x} \in \Omega} |\mu(\mathbf{x}) - \nu(\mathbf{x})|$$

- ▶ **Mixing Time**

$$t_{\text{mix}}(\varepsilon) = \min\{t \in \mathbb{N} : \|P^t(\mathbf{x}, \cdot) - \pi\| \leq \varepsilon \text{ for all } \mathbf{x} \in \Omega\}$$

Logit Dynamics

Definition

$\mathcal{G} = ([n], \mathcal{S}, \mathcal{U})$. Logit dynamics for G is the Markov chain with state space $\Omega = S_1 \times \cdots \times S_n$ and transition matrix

$$P(\mathbf{x}, \mathbf{y}) = \frac{1}{n} \sum_{i=1}^n \frac{e^{\beta u_i(\mathbf{x}_{-i}, y_i)}}{T_i(\mathbf{x})} \mathbb{I}_{\{y_j = x_j \text{ for every } j \neq i\}}$$

Logit Dynamics

Definition

$\mathcal{G} = ([n], \mathcal{S}, \mathcal{U})$. Logit dynamics for G is the Markov chain with state space $\Omega = S_1 \times \cdots \times S_n$ and transition matrix

$$P(\mathbf{x}, \mathbf{y}) = \frac{1}{n} \sum_{i=1}^n \frac{e^{\beta u_i(\mathbf{x}_{-i}, y_i)}}{T_i(\mathbf{x})} \mathbb{I}_{\{y_j = x_j \text{ for every } j \neq i\}}$$

Logit Dynamics defines an ergodic Markov chain

- What is the **stationary distribution** π ?

Logit Dynamics

Definition

$\mathcal{G} = ([n], \mathcal{S}, \mathcal{U})$. Logit dynamics for G is the Markov chain with state space $\Omega = S_1 \times \cdots \times S_n$ and transition matrix

$$P(\mathbf{x}, \mathbf{y}) = \frac{1}{n} \sum_{i=1}^n \frac{e^{\beta u_i(\mathbf{x}_{-i}, y_i)}}{T_i(\mathbf{x})} \mathbb{I}_{\{y_j = x_j \text{ for every } j \neq i\}}$$

Logit Dynamics defines an ergodic Markov chain

- ▶ What is the stationary distribution π ?
- ▶ What is the **stationary expected social welfare** $\mathbf{E}_\pi [W]$?

Logit Dynamics

Definition

$\mathcal{G} = ([n], \mathcal{S}, \mathcal{U})$. Logit dynamics for G is the Markov chain with state space $\Omega = S_1 \times \cdots \times S_n$ and transition matrix

$$P(\mathbf{x}, \mathbf{y}) = \frac{1}{n} \sum_{i=1}^n \frac{e^{\beta u_i(\mathbf{x}_{-i}, y_i)}}{T_i(\mathbf{x})} \mathbb{I}_{\{y_j = x_j \text{ for every } j \neq i\}}$$

Logit Dynamics defines an ergodic Markov chain

- ▶ What is the stationary distribution π ?
- ▶ What is the stationary expected social welfare $\mathbf{E}_\pi [W]$?
- ▶ **How long it takes to get close to the stationary distribution?**

Logit Dynamics

Some recent related works

[Montanari, Saberi, FOCS'09]:

Hitting time of the best Nash equilibrium in a classical “game”
(Ising model for ferromagnetism. Applications to the spread of innovations in a network)

Logit Dynamics

Some recent related works

[Montanari, Saberi, FOCS'09]:

Hitting time of the best Nash equilibrium in a classical “game”
(Ising model for ferromagnetism. Applications to the spread of innovations in a network)

[Asadpour, Saberi, WINE'09]:

Hitting time of the *neighborhood* of best Nash equilibria for
Atomic Selfish Routing and Load Balancing.

Logit Dynamics

Some recent related works

[Montanari, Saberi, FOCS'09]:

Hitting time of the best Nash equilibrium in a classical “game” (Ising model for ferromagnetism. Applications to the spread of innovations in a network)

[Asadpour, Saberi, WINE'09]:

Hitting time of the *neighborhood* of best Nash equilibria for Atomic Selfish Routing and Load Balancing.

They study **hitting time of Nash equilibria**. We propose **stationary distribution as equilibrium concept**.

Logit Dynamics

Some recent related works

[Montanari, Saberi, FOCS'09]:

Hitting time of the best Nash equilibrium in a classical “game” (Ising model for ferromagnetism. Applications to the spread of innovations in a network)

[Asadpour, Saberi, WINE'09]:

Hitting time of the *neighborhood* of best Nash equilibria for Atomic Selfish Routing and Load Balancing.

They study hitting time of Nash equilibria. We propose stationary distribution as equilibrium concept.

Nash equilibria	Stationary distribution of logit dynamics
Not Unique	Unique

Logit Dynamics

Some recent related works

[Montanari, Saberi, FOCS'09]:

Hitting time of the best Nash equilibrium in a classical “game” (Ising model for ferromagnetism. Applications to the spread of innovations in a network)

[Asadpour, Saberi, WINE'09]:

Hitting time of the *neighborhood* of best Nash equilibria for Atomic Selfish Routing and Load Balancing.

They study hitting time of Nash equilibria. We propose stationary distribution as equilibrium concept.

Nash equilibria	Stationary distribution of logit dynamics
Not Unique Local	Unique Global

Example: Matching Pennies

- ▶ If both choose the same side then Player 1 wins;
- ▶ If they choose different sides then Player 2 wins

	H	T
H	$+1, -1$	$-1, +1$
T	$-1, +1$	$+1, -1$

Example: Matching Pennies

- ▶ If both choose the same side then Player 1 wins;
- ▶ If they choose different sides then Player 2 wins

	H	T
H	$+1, -1$	$-1, +1$
T	$-1, +1$	$+1, -1$

No pure Nash, one mixed Nash $\sigma_1 = \sigma_2 = (1/2, 1/2)$

Example: Matching Pennies

- ▶ If both choose the same side then Player 1 wins;
- ▶ If they choose different sides then Player 2 wins

	H	T
H	$+1, -1$	$-1, +1$
T	$-1, +1$	$+1, -1$

No pure Nash, one mixed Nash $\sigma_1 = \sigma_2 = (1/2, 1/2)$

Logit dynamics

Example:

$$\sigma_1(H | (-, T)) =$$

Example: Matching Pennies

- ▶ If both choose the same side then Player 1 wins;
- ▶ If they choose different sides then Player 2 wins

	H	T
H	$+1, -1$	$-1, +1$
T	$-1, +1$	$+1, -1$

No pure Nash, one mixed Nash $\sigma_1 = \sigma_2 = (1/2, 1/2)$

Logit dynamics

Example:

$$\sigma_1(H | (-, T)) = \frac{e^{\beta u_1(H, T)}}{e^{\beta u_1(H, T)} + e^{\beta u_1(T, T)}}$$

Example: Matching Pennies

- ▶ If both choose the same side then Player 1 wins;
- ▶ If they choose different sides then Player 2 wins

	H	T
H	$+1, -1$	$-1, +1$
T	$-1, +1$	$+1, -1$

No pure Nash, one mixed Nash $\sigma_1 = \sigma_2 = (1/2, 1/2)$

Logit dynamics

Example:

$$\begin{aligned}
 \sigma_1(H | (-, T)) &= \frac{e^{\beta u_1(H, T)}}{e^{\beta u_1(H, T)} + e^{\beta u_1(T, T)}} \\
 &= \frac{e^{-\beta}}{e^{-\beta} + e^{\beta}}
 \end{aligned}$$

Example: Matching Pennies

- ▶ If both choose the same side then Player 1 wins;
- ▶ If they choose different sides then Player 2 wins

	H	T
H	$+1, -1$	$-1, +1$
T	$-1, +1$	$+1, -1$

No pure Nash, one mixed Nash $\sigma_1 = \sigma_2 = (1/2, 1/2)$

Logit dynamics

Example:

$$\begin{aligned}
 \sigma_1(H | (-, T)) &= \frac{e^{\beta u_1(H, T)}}{e^{\beta u_1(H, T)} + e^{\beta u_1(T, T)}} \\
 &= \frac{e^{-\beta}}{e^{-\beta} + e^{\beta}} = \frac{1}{1 + e^{2\beta}}
 \end{aligned}$$

Matching Pennies

Logit dynamics

$$P = \frac{1}{2} \left(\begin{array}{c|cccc} & HH & HT & TH & TT \\ \hline HH & 1 & b & (1-b) & 0 \\ HT & (1-b) & 1 & 0 & b \\ TH & b & 0 & 1 & (1-b) \\ TT & 0 & (1-b) & b & 1 \end{array} \right)$$

$$b = \frac{1}{1+e^{-2\beta}}.$$

Matching Pennies

Logit dynamics

$$P = \frac{1}{2} \left(\begin{array}{c|cccc} & HH & HT & TH & TT \\ \hline HH & 1 & b & (1-b) & 0 \\ HT & (1-b) & 1 & 0 & b \\ TH & b & 0 & 1 & (1-b) \\ TT & 0 & (1-b) & b & 1 \end{array} \right)$$

$$b = \frac{1}{1+e^{-2\beta}}.$$

Matching Pennies

Logit dynamics

$$P = \frac{1}{2} \left(\begin{array}{c|cccc} & HH & HT & TH & TT \\ \hline HH & 1 & b & (1-b) & 0 \\ HT & (1-b) & 1 & 0 & b \\ TH & b & 0 & 1 & (1-b) \\ TT & 0 & (1-b) & b & 1 \end{array} \right)$$

$$b = \frac{1}{1+e^{-2\beta}}.$$

$$\blacktriangleright \pi = \frac{1}{4}(1, 1, 1, 1)$$

$$\mathbf{E}_{\pi}[W] = 0$$

Matching Pennies

Logit dynamics

$$P = \frac{1}{2} \left(\begin{array}{c|cccc} & HH & HT & TH & TT \\ \hline HH & 1 & b & (1-b) & 0 \\ HT & (1-b) & 1 & 0 & b \\ TH & b & 0 & 1 & (1-b) \\ TT & 0 & (1-b) & b & 1 \end{array} \right)$$

$$b = \frac{1}{1+e^{-2\beta}}.$$

$$\blacktriangleright \pi = \frac{1}{4}(1, 1, 1, 1)$$

$$\mathbf{E}_{\pi}[W] = 0$$

$$\blacktriangleright \|P^3(\mathbf{x}, \cdot) - \pi\| < 1/2 \text{ so}$$

$$t_{\text{mix}} = \mathcal{O}(1)$$

(upper bounded by a constant for every β)

Logit Dynamics

Potential games

$\mathcal{G} = ([n], \mathcal{S}, \mathcal{U})$. $\Phi : S_1 \times \cdots \times S_n \rightarrow \mathbb{R}$ **exact potential** if
for every profile \mathbf{x} , for every player i , and for every action y

$$u_i(\mathbf{x}_{-i}, y) - u_i(\mathbf{x}) = -[\Phi(\mathbf{x}_{-i}, y) - \Phi(\mathbf{x})]$$

Logit Dynamics

Potential games

$\mathcal{G} = ([n], \mathcal{S}, \mathcal{U})$. $\Phi : S_1 \times \cdots \times S_n \rightarrow \mathbb{R}$ **exact potential** if for every profile \mathbf{x} , for every player i , and for every action y

$$u_i(\mathbf{x}_{-i}, y) - u_i(\mathbf{x}) = -[\Phi(\mathbf{x}_{-i}, y) - \Phi(\mathbf{x})]$$

Logit dynamics for potential games

The stationary distribution is the Gibbs one

$$\pi(\mathbf{x}) = \frac{e^{-\beta\Phi(\mathbf{x})}}{Z}$$

Logit Dynamics

Potential games

$\mathcal{G} = ([n], \mathcal{S}, \mathcal{U})$. $\Phi : S_1 \times \cdots \times S_n \rightarrow \mathbb{R}$ **exact potential** if for every profile \mathbf{x} , for every player i , and for every action y

$$u_i(\mathbf{x}_{-i}, y) - u_i(\mathbf{x}) = -[\Phi(\mathbf{x}_{-i}, y) - \Phi(\mathbf{x})]$$

Logit dynamics for potential games

The stationary distribution is the Gibbs one

$$\pi(\mathbf{x}) = \frac{e^{-\beta\Phi(\mathbf{x})}}{Z}$$

Observation [Blume'93]

For $\beta \rightarrow \infty$ the stationary distribution π is concentrated over the global minima of the potential function.

Logit Dynamics

Potential games

$\mathcal{G} = ([n], \mathcal{S}, \mathcal{U})$. $\Phi : S_1 \times \cdots \times S_n \rightarrow \mathbb{R}$ **exact potential** if for every profile \mathbf{x} , for every player i , and for every action y

$$u_i(\mathbf{x}_{-i}, y) - u_i(\mathbf{x}) = -[\Phi(\mathbf{x}_{-i}, y) - \Phi(\mathbf{x})]$$

Logit dynamics for potential games

The stationary distribution is the Gibbs one

$$\pi(\mathbf{x}) = \frac{e^{-\beta\Phi(\mathbf{x})}}{Z}$$

Observation [Blume'93]

For $\beta \rightarrow \infty$ the stationary distribution π is concentrated over the global minima of the potential function.

$$\Rightarrow \frac{\text{opt}(W)}{\mathbf{E}_{\pi}[W]} \rightarrow \text{Price of Stability}$$

Chicken Game

Description

- ▶ If both STOP then none wins;
- ▶ If both PASS then both lose;
- ▶ If one PASSes and one STOP, then who passes win.

	S	P
S	$(0, 0)$	$(0, 1)$
P	$(1, 0)$	$(-1, -1)$

Chicken Game

Description

- ▶ If both STOP then none wins;
- ▶ If both PASS then both lose;
- ▶ If one PASSes and one STOP, then who passes win.

	S	P
S	$(0, 0)$	$(0, 1)$
P	$(1, 0)$	$(-1, -1)$

Two pure Nash, one mixed Nash.

Potential game: stationary distribution is for free.

Chicken Game

Description

- ▶ If both STOP then none wins;
- ▶ If both PASS then both lose;
- ▶ If one PASSes and one STOP, then who passes win.

	<i>S</i>	<i>P</i>
<i>S</i>	(0, 0)	(0, 1)
<i>P</i>	(1, 0)	(-1, -1)

Two pure Nash, one mixed Nash.

Potential game: stationary distribution is for free.

Stationary expected social welfare

$$\begin{aligned}\pi(SS) &= \pi(PP) = \frac{1}{2(1+e^\beta)} \\ \pi(SP) &= \pi(PS) = \frac{1}{2(1+e^{-\beta})}\end{aligned}$$

$$\mathbf{E}_\pi[W] = \frac{e^\beta - 1}{e^\beta + 1}$$

Chicken Game

Description

- ▶ If both STOP then none wins;
- ▶ If both PASS then both lose;
- ▶ If one PASSes and one STOP, then who passes win.

	S	P
S	$(0, 0)$	$(0, 1)$
P	$(1, 0)$	$(-1, -1)$

Two pure Nash, one mixed Nash.

Potential game: stationary distribution is for free.

Stationary expected social welfare

$$\begin{aligned}\pi(SS) &= \pi(PP) = \frac{1}{2(1+e^\beta)} \\ \pi(SP) &= \pi(PS) = \frac{1}{2(1+e^{-\beta})}\end{aligned}$$

$$\mathbf{E}_\pi[W] = \frac{e^\beta - 1}{e^\beta + 1}$$

Observations

- ▶ Expected social welfare **tends to** 1 for $\beta \rightarrow \infty$;

Chicken Game

Description

- ▶ If both STOP then none wins;
- ▶ If both PASS then both lose;
- ▶ If one PASSes and one STOP, then who passes win.

	S	P
S	$(0, 0)$	$(0, 1)$
P	$(1, 0)$	$(-1, -1)$

Two pure Nash, one mixed Nash.

Potential game: stationary distribution is for free.

Stationary expected social welfare

$$\begin{aligned}\pi(SS) &= \pi(PP) = \frac{1}{2(1+e^\beta)} \\ \pi(SP) &= \pi(PS) = \frac{1}{2(1+e^{-\beta})}\end{aligned}$$

$$\mathbf{E}_\pi[W] = \frac{e^\beta - 1}{e^\beta + 1}$$

Observations

- ▶ Expected social welfare tends to 1 for $\beta \rightarrow \infty$;
- ▶ Expected social welfare is **fair**.

Chicken Game

Mixing time

Mixing time is **exponential** in β

$$t_{\text{mix}} = \Theta(e^{\beta})$$

Chicken Game

Mixing time

Mixing time is exponential in β

$$t_{\text{mix}} = \Theta(e^{\beta})$$

Intuition

- ▶ The two Nash equilibria have the same stationary probability;
- ▶ When β is *large*, it takes a long time to go from one Nash equilibrium to the other one.

Chicken Game

Mixing time

Mixing time is exponential in β

$$t_{\text{mix}} = \Theta(e^{\beta})$$

Intuition

- ▶ The two Nash equilibria have the same stationary probability;
- ▶ When β is *large*, it takes a long time to go from one Nash equilibrium to the other one.

Generalization

Chicken Game is an anti-coordination game. The results extend to all **coordination** and **anti-coordination** games.

OR-game

Definition

A **trivial** game with a **non-trivial** mixing time analysis.

OR-game

Definition

A **trivial** game with a **non-trivial** mixing time analysis.

Every player has two strategies, say $\{0, 1\}$, and each player pays the OR of the strategies of all players (including herself).

$$u_i(\mathbf{x}) = \begin{cases} 0 & \text{if } \mathbf{x} = \mathbf{0}; \\ -1 & \text{otherwise.} \end{cases}$$

OR-game

Definition

A **trivial** game with a **non-trivial** mixing time analysis.

Every player has two strategies, say $\{0, 1\}$, and each player pays the OR of the strategies of all players (including herself).

$$u_i(\mathbf{x}) = \begin{cases} 0 & \text{if } \mathbf{x} = \mathbf{0}; \\ -1 & \text{otherwise.} \end{cases}$$

Almost every profile is Nash equilibrium (except profiles with exactly one 1)

$$W(\text{best Nash eq.}) = 0; \quad W(\text{worst Nash eq.}) = -n$$

OR-game

Definition

A **trivial** game with a **non-trivial** mixing time analysis.

Every player has two strategies, say $\{0, 1\}$, and each player pays the OR of the strategies of all players (including herself).

$$u_i(\mathbf{x}) = \begin{cases} 0 & \text{if } \mathbf{x} = \mathbf{0}; \\ -1 & \text{otherwise.} \end{cases}$$

Almost every profile is Nash equilibrium (except profiles with exactly one 1)

$$W(\text{best Nash eq.}) = 0; \quad W(\text{worst Nash eq.}) = -n$$

Expected social welfare

$$\mathbf{E}_\pi [W] = -\frac{(2^n - 1)e^{-\beta}}{1 + (2^n - 1)e^{-\beta}} \cdot n$$

OR-game

Definition

A **trivial** game with a **non-trivial** mixing time analysis.

Every player has two strategies, say $\{0, 1\}$, and each player pays the OR of the strategies of all players (including herself).

$$u_i(\mathbf{x}) = \begin{cases} 0 & \text{if } \mathbf{x} = \mathbf{0}; \\ -1 & \text{otherwise.} \end{cases}$$

Almost every profile is Nash equilibrium (except profiles with exactly one 1)

$$W(\text{best Nash eq.}) = 0; \quad W(\text{worst Nash eq.}) = -n$$

Expected social welfare

$$\mathbf{E}_\pi [W] = -\frac{(2^n - 1)e^{-\beta}}{1 + (2^n - 1)e^{-\beta}} \cdot n \quad \mathbf{E}_\pi [W] \rightarrow 0 \quad \text{for } \beta \rightarrow \infty$$

OR-game

Mixing time

$$t_{\text{mix}} \approx \begin{cases} \mathcal{O}(n \log n) & \text{if } \beta < \log n \end{cases}$$

OR-game

Mixing time

$$t_{\text{mix}} \approx \begin{cases} \mathcal{O}(n \log n) & \text{if } \beta < \log n \\ \Theta(n^c) & \text{if } \beta = c \log n, c > 1 \text{ constant} \end{cases}$$

OR-game

Mixing time

$$t_{\text{mix}} \approx \begin{cases} \mathcal{O}(n \log n) & \text{if } \beta < \log n \\ \Theta(n^c) & \text{if } \beta = c \log n, c > 1 \text{ constant} \\ \Theta(2^n) & \text{otherwise} \end{cases}$$

OR-game

Mixing time

$$t_{\text{mix}} \approx \begin{cases} \mathcal{O}(n \log n) & \text{if } \beta < \log n \\ \Theta(n^c) & \text{if } \beta = c \log n, c > 1 \text{ constant} \\ \Theta(2^n) & \text{otherwise} \end{cases}$$

Intuition

- ▶ When β is *large* the stationary distribution is concentrated in profile **0**;
- ▶ From a profile with at least two 1's, every players choose u.a.r. over $\{0, 1\}$

OR-game

Mixing time

$$t_{\text{mix}} \approx \begin{cases} \mathcal{O}(n \log n) & \text{if } \beta < \log n \\ \Theta(n^c) & \text{if } \beta = c \log n, c > 1 \text{ constant} \\ \Theta(2^n) & \text{otherwise} \end{cases}$$

Intuition

- ▶ When β is *large* the stationary distribution is concentrated in profile **0**;
- ▶ From a profile with at least two 1's, every players choose u.a.r. over $\{0, 1\}$

Proof techniques:

- ▶ Path-coupling for the upper bound;
- ▶ Bottleneck ratio for the lower bound.

Further and Future Investigations

- ▶ **Logit dynamics for more interesting (class of) games;**
 - ▶ Potential games: Mixing time depends on the *shape* of the potential function
(Lipschitz conditions, Number of local minima, Maximum *Slope*, ...);
 - ▶ Stationary expected social welfare vs PoA / PoS for classical games;

Further and Future Investigations

- ▶ Logit dynamics for more *interesting* (class of) games;
 - ▶ Potential games: Mixing time depends on the *shape* of the potential function
(Lipschitz conditions, Number of local minima, Maximum *Slope*, ...);
 - ▶ Stationary expected social welfare vs PoA / PoS for classical games;
- ▶ **Other randomized best response dynamics**
 - ▶ E.g. All players play simultaneously;

Further and Future Investigations

- ▶ Logit dynamics for more *interesting* (class of) games;
 - ▶ Potential games: Mixing time depends on the *shape* of the potential function (Lipschitz conditions, Number of local minima, Maximum *Slope*, ...);
 - ▶ Stationary expected social welfare vs PoA / PoS for classical games;
- ▶ Other randomized best response dynamics
 - ▶ E.g. All players play simultaneously;
- ▶ **Connections with other disciplines**
 - ▶ Statistical Physics;
 - ▶ Evolutionary biology??

Further and Future Investigations

- ▶ Logit dynamics for more *interesting* (class of) games;
 - ▶ Potential games: Mixing time depends on the *shape* of the potential function (Lipschitz conditions, Number of local minima, Maximum *Slope*, ...);
 - ▶ Stationary expected social welfare vs PoA / PoS for classical games;
- ▶ Other randomized best response dynamics
 - ▶ E.g. All players play simultaneously;
- ▶ Connections with other disciplines
 - ▶ Statistical Physics;
 - ▶ Evolutionary biology??
- ▶ **What happens when mixing time is exponential?**
 - ▶ Chaotic behavior during transient phase?
 - ▶ Polynomially *almost* stationary distributions?

References

Vincenzo Auletta, Diodato Ferraioli, Francesco Pasquale, and Giuseppe Persiano.

Mixing time and Stationary Expected Social Welfare of Logit Dynamics.

Submitted, 2010 (<http://arxiv.org/abs/1002.3474>).

References

Vincenzo Auletta, Diodato Ferraioli, Francesco Pasquale, and Giuseppe Persiano.

Mixing time and Stationary Expected Social Welfare of Logit Dynamics.

Submitted, 2010 (<http://arxiv.org/abs/1002.3474>).

Thank you!